

RAJASTHAN TECHNICAL UNIVERSITY, KOTA

Syllabus

3rd Year - V Semester: B.Tech. : Mechanical Engineering

5ME3-01: MECHATRONIC SYSTEMS

Credit: 2 Max. Marks: 100(IA: 20, ETE:80)
2L+0T+0P End Term Exam: 2 Hours

SN	CONTENTS	Hours
1	Introduction: Objective, scope and outcome of the course.	1
2	Overview of Mechatronics: Historical perspective, Definition, Applications, Block diagram of Mechatronic system, Functions of Mechatronics Systems, Systems Engineering, Verification Vs Validation, Benefits of mechatronics in manufacturing.	2
	Electrical and Electronic Systems: Electrical circuits and Kirchhoff's laws, Network Theorems and AC circuit Analysis, Transformers, Analog Devices, Signal Conditioning, Digital Electronics, Data Acquisition systems.	3
3	Modeling, Analysis and Control of Physical Systems: Basics of System Modeling: LTI and LTV systems, Need for modeling, Types of modeling, Steps in modeling, Building blocks of models, Modelling of one and two degrees of freedom systems, Modeling of Electromechanical systems, Mechanical Systems, Fluid systems, Thermal systems; Dynamic Responses, System Transfer Functions, State Space Analysis and System Properties, Stability Analysis using Root Locus Method, Stability Analysis using Bode Plots, PID Controllers (with and without Time Delay)	5
4	Sensors and Actuators: Static characteristics of sensors and actuators, Position, Displacement and Proximity Sensors, Force and torque sensors, Pressure sensors, Flow sensors, Temperature sensors, Acceleration sensors, Level sensors, Light sensors, Smart material sensors, Micro and Nano sensors, Selection criteria for sensors, Actuators: Electrical Actuators (Solenoids, Relays, Diodes, Thyristors, Triacs, BJT, FET, DC motor, Servo motor, BLDC motor, AC motor, Stepper motors), Hydraulic and Pneumatic actuators, Design of Hydraulic and Pneumatic circuits, Piezoelectric	7
5	actuators, Shape memory alloys. Microprocessors, Microcontrollers and Programmable Logic Controllers: Logic Concepts and Design, System Interfaces, Communication and Computer Networks, Fault Analysis in Mechatronic Systems, Synchronous and Asynchronous Sequential Systems, Architecture, Microcontrollers.	3
6	Programmable Logic Controllers (PLCs): Architecture, Number Systems Basics of PLC Programming, Logics, Timers and Counters, Application on real time industrial automation systems.	4
	Case Studies: Design of pick and place robot, Car engine management system, Automated manufacturing system, Automatic camera, Automatic parking system, Safety devices and systems.	3

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